



- Please do not use in the following environment
 - Direct sunlight
 - Places with high humidity or easy condensation
 - Places containing corrosive gases
 - Places subject to severe vibration or shock
- Connection and installation
 - Do not use the sensor in an unstable state immediately after the power is turned on,(recommended to test after 30 minutes of power on to achieve desired accuracy)
 - Be sure to carry out wiring with the power off. If a wrong wiring occurs, it will cause a malfunction
 - Please make sure that the power supply voltage is within the rated value before powering on
 - Please use rated load
 - The RS485 signal line should not be short-circuited with the power supply,otherwise it may cause product failure or damage the product
 - When installing the sensor,do not subject the sensor to severe external forces(such as hammering,etc) as this may damage the sensor performance
 - Do not bend the lead out of the cable with excessive force,and avoid applying pressure such as pulling
- Cleaning
 - Thinner will corrode the surface of the filter, it is best to avoid using it
 - If there is dust on the surface,please wipe it gently with a dry dust-free cloth

- Do not use in an environment with flammable, explosive or corrosive gases
- The RS485 communication line should not be too long
- Do not disassemble, repair or modify this product without authorization
- This product is dangerous, please do not look directly at the laser or observe the optical system through the lens

- When the product is scrapped, please dispose of it as industrial waste

- This sensor series are Class 3 laser products, please do not look directly at the laser or observe it through the laser. Warning labels are affixed to this series, please use them according to label instructions.

Products series		Laser distance measuring sensor
Model	RS-485	PDB-CM8DGR
	4...20mA	PDB-CM8TGI
	0...10V	PDB-CM8TGU
Measuring range		0.2...8m ^③
Measuring accuracy		±1%F.S. ^②
Repeated stability		±1%F.S. ^②
Supply voltage		RS-485:10...30VDC;4...20mA/0...10V/12...24VDC
Consumption power		≤700mW
Load current		50mA
Voltage drop		<2.5V
Light source type		Infrared laser(850nm);Laser level:class 3R
Functional principle		TOF
Average optical power		20mW
Pulse duration		50ns
Pulse frequency		10MHZ
Detection frequency		100HZ
Light spot size		RS-485:90°90mm(At 5m);4...20mA/0...10V:90°90mm(At 5m)
Dimension		65mm*51mm*23mm
Resolution		1mm
Output 1		Digital value:RS-485(Support ModBus protocol);Analog:4...20mA(Load resistance<300Ω), Analog:0...10V(Load resistance>5K)
Output 2		Switch value:PUSH-PULL/NPN/PNP/NO/NC Settable
Distance setting		RS-485:Keypress/RS-485 setting:4...20mA/0...10V:Keypress setting
Indicator		Power indicator: Green LED>Action indicator: Yellow LED, Yellow LED
Return difference		3cm below 2m, ≤2% above 2m
Protection circuit		Short circuit,reverse polarity
Built-in function		Button to lock; button to unlock; action point setting;Output setting; single point teach; Window teach mode setting; factory date reset;Slave address&Port rate setting(only for RS-485)
Service environment		Operating temperature: -10...+50℃
Anti ambient light		Incandescent light: <20,000lux
Protection degree		IP67
Material		Housing:ABS;Lens cover:PMMA
Vibration resistant		10...55Hz Double amplitude 1mm,2hrs each for X,Y,Z direction
Impulse withstand		500m/s ² (About 50G), 3 times each for X,Y,Z direction
Connection way		RS-485:2m 5pins PVC cable;4...20mA:2m 4pins PVC cable;0...10V:2m 4pins PVC cable
Accessory		Screw (M4×35mm) ×2, Nut×2, Washer×2, Mounting bracket, Operation manual

The diagram shows the back of the device with the following components labeled:

- T Button**: Located on the left side of the device.
- S Button**: Located on the right side of the device.
- Power indicator**: A small LED indicator located below the T Button.
- L1 Indicator**: A small LED indicator located below the S Button.
- L2 Indicator**: A small LED indicator located below the S Button.

1.Button

Used to set the unlock,switch output logic of the sensor,operating point,data filtering,analog ,reset.

T	Toggle button	Switch button
S	Set button	Set button

2.Button Setting function




Function list
Action point single point teaching TEACH A
Operation point window teaching TEACH A, TEACH B
Output logic: NO/NC selection
Output status out:NPN/PNP/PUSH-PULL(PP)selection
Filter level Aver: FAST / MEDIUM / SLOW selection
Analog mapping 4mA
Analog mapping 20mA
Reset
Slave address :0x80-0xF4 (only for RS-485)
Port rate:115200/57600/38400/19200/9600 (only for RS-485)

3.Indicator

Used as power indication,sensing indication,alarm indication,setting indication

Product name	Color	Always on/off	Flashing
LP	Green	Power indication	—
L1	Yellow	Sensing indication	—
L2	Yellow		

Indicator status description

Indicator information	Indicator status	Status information
Action point is sensed		L1 and L2 are on at the same time
Action point is not sensed		L1 and L2 are off at the same time
Switch output overload		L1 and L2 flash asynchronously at a frequency of 6.25Hz

Technical drawing of the remote control showing three views: front, side, and top. The dimensions are provided in millimeters.

Front View Dimensions:

- Overall width: 51
- Overall height: 65
- Top edge width: 41
- Bottom edge width: 4.5
- Distance from top edge to button: 4.4
- Distance from bottom edge to button: 4.4
- Distance from left edge to button: 5.9
- Distance from right edge to button: 4.75
- Distance from bottom edge to indicator: 18.75

Side View Dimensions:

- Overall thickness: 23
- Distance from top edge to receiver: 17.5
- Distance from receiver to emitter: 14.8

Top View Dimensions:

- Overall width: 51
- Overall height: 65
- Distance from left edge to button: 8.6
- Distance from right edge to button: 4.4
- Distance from bottom edge to button: 4.4
- Distance from top edge to button: 4.4
- Distance from left edge to indicator: 4.4
- Distance from right edge to indicator: 4.4
- Distance from bottom edge to indicator: 4.4
- Distance from top edge to indicator: 4.4

Labels:

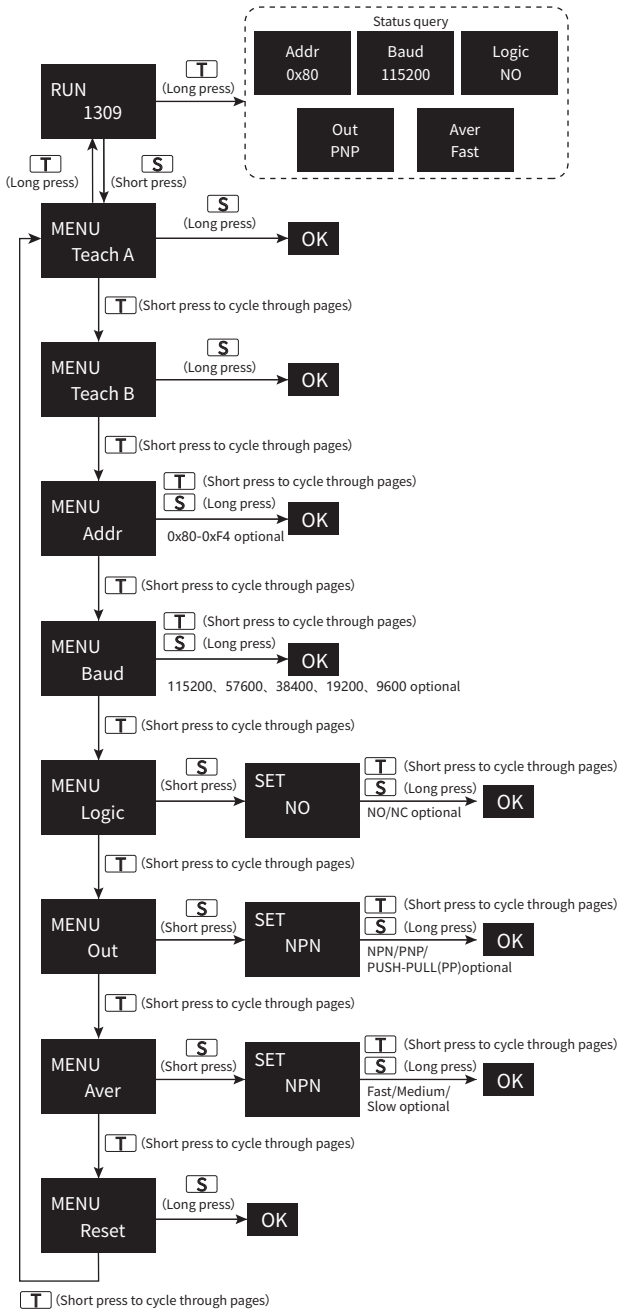
- Receiver
- Emitter
- Button
- Indicator

- Self-lock and Unlock

- 1.Unlock:When the key is in the self-locking state, long press the S key for 4-6S.
When the screen displays UN LOCK, you can press the key.
- 2.Self-lock:if the button is not pressed within 10 minutes of power-on, it locks itself.After pressing the button to LOCK itself, the screen displays LOCK.The corresponding setting operation cannot be performed.

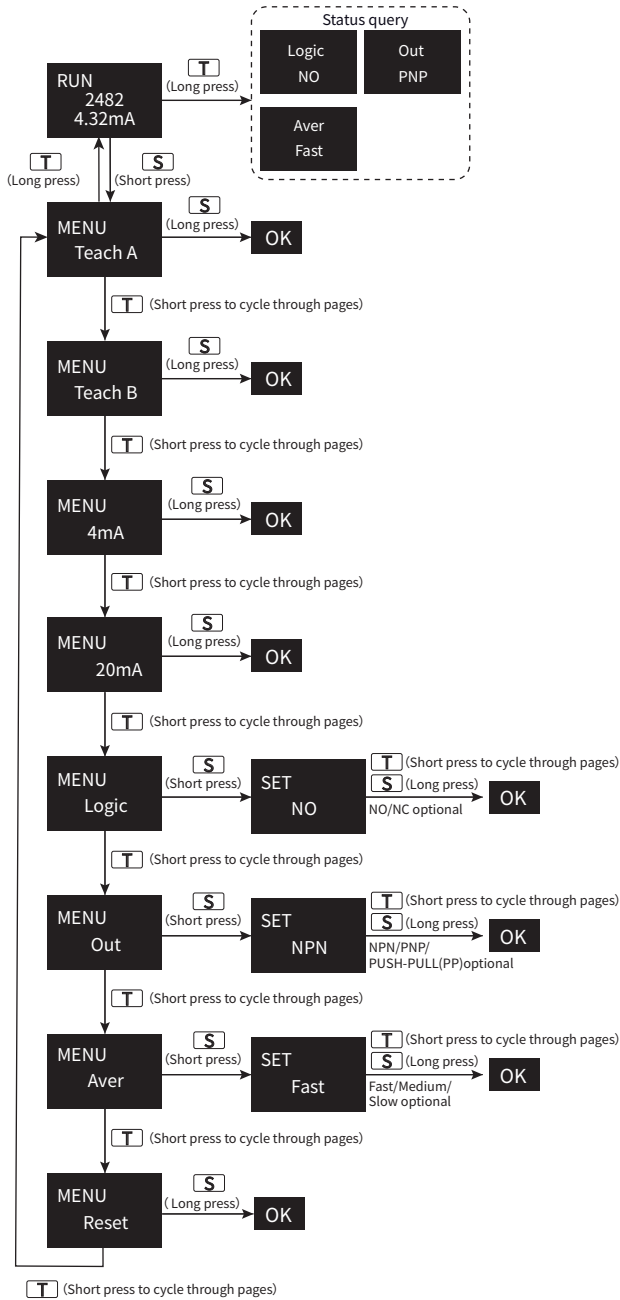
- PDB-CM**485 Output series

Perform the following operations in the unlocked state:

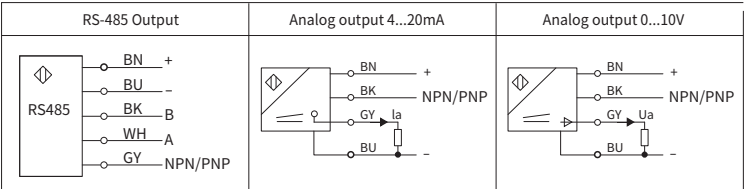


- PDB-CM**Analog current

Perform the following operations in the unlocked state:



■ Wiring diagram



Remark: The sensors are equipped with shielded cables,NPN/PNP is the switch output.
RS-485 output:The black and white lines A and B must not be reversed and A and B cannot be short-circuited with the power line " + -".
Analog output: The gray line Ia cannot be short-circuited with the power line " + -", and there is a small shielded wire in the gray line.

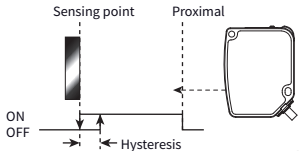
■ Function Description

- Action point single point teaching TEACH A

Within the sensing range,select the first distance value as the operating point and fix the product and the target.When entering the " Teach A" mode, long press the S key to start teaching.After success,release the key to automatically return to the initial state of the previous level to complete the teaching of the first action point.Then enter the "Teach B" mode and then long press the S key to start teaching. After success,release the key to automatically return to the initial state of the previous level. For the operation of analog output or 485 output,please refer to "Operation manual".

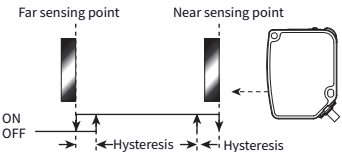
After teaching at specified position,output ON from the position to the near end of the detection range.

Actual operating point: Set value * 101%;Actual exit point:Less than set value * 102%.



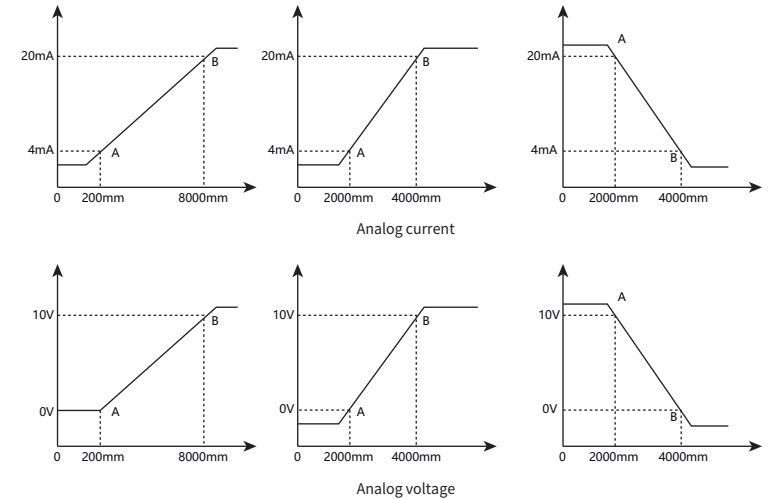
- Operation point window teaching TEACH A, TEACH B

Within the sensing range,select the first distance value as the operating point and fix the product and the target.Enter the "Teach A" mode and then long press the S key to start teaching.After success,release the key to automatically return to the initial state of the previous level to complete the teaching of the first action point.Then enter the "Teach B" mode and then long press the S key to start teaching. After success,release the key to automatically return to the initial state of the previous level. For the operation of analog output or 485 output,please refer to "Operation manual". If you want to return to single-point teaching after completing window teaching, only need to operate "single point teaching",the product will automatically clear the last window teaching value. Actual operating point: Set value * 101%; Actual exit point:Less than set value * 102%. After teaching at the specified 2 positions,the output is ON within the range between 2 positions.



- Analog mapping: 4mA, 20mA

Within the sensing range,after selecting the "current" mode,enter "4mA" or "20mA,select the first distance value as the 4mA mapping point(or 20mA mapping point),and fix the sensor and target.The position of 4mA and 20mA(A,B) points within the effective range can be arbitrarily set,And the distance between (a, b) points is greater than 5% of the current distance, the setting is successful.Otherwise,the setting will fail.The default(A,B)is(4mA,20mA).For the operation of analog output,please refer to "Operation manual".



■ Data transmission (only for RS485)

- ◆Baud rate:115200(default)
- ◆Parity check:None
- ◆Data bits:8

- ◆Stop bit:1
- ◆Slave default address:0x80

Note:The default address is 0x80.Different slave addresses or different baud rates will have different redundancy checks.

1.Master station request message format(Command to read distance information):

Slave address	Function code	Data start address	Data volume (Unit: words)	Redundancy check CRC16-2
80	03	9C 7D	MSB:00 LSB:01	LSB:24 MSB:53

Slave station response message format:

Slave address	Function code	Bytes	Data	Redundancy check CRC16-2
80	03	02	MSB LSB LSB MSB	

The host computer communicates through RS485,and the sensor data read out needs to be calculated by the following method to obtain actual measured value.

(1)Convert the fourth and fifth bytes in the reply packet from the slave station into decimal. The unit is mm.
(2)When the distance is less than 150mm, it is a blind area, and the actual measured value =150; When the distance is greater than 11000mm, the measured range is exceeded, and the actual measured value =11000;
For example:The master request message:80 03 9C 7D 00 01 24 53
The slave response message:80 03 02 09 A1 43 B2

The 4th and 5th bytes of the slave's response message are 09 A1,converted to decimal 2465, Actual distance value=2465.

Return:If the setting is successful,the original instruction will be returned;If it fails,an error instruction will be returned.

2. The master request message format(The address broadcast call command):

Slave address	Function code	Address where data is stored	Data volume (Unit: words)	Redundancy check CRC16-2
00	06	9C 7E	00 81	06 33

The address broadcast call command is used when the address originally set by the sensor is unclear.Modify any current address value to the required value through broadcast command. Address modification range:0x80~0xF4

For example:The address originally set by the sensor is unknown,and you want to set the address to 0x81
Then send instructions via RS485 bus:00 06 9C 7E 00 81 06 33
The address originally set by the sensor is unknown,and you want to set the address to 0x82
Then send instructions via RS485 bus:00 06 9C 7E 00 82 46 32

Return:There is no return no matter the setting is successfully or fails.

3.Master station request message format(Modified address command):

Slave address	Function code	Address where data is stored	Modify value	Redundancy check CRC16-2
80	06	9C 7E	00 85	LSB:18 MSB:30

Slave station response message format:

Slave address	Function code	Address where data is stored	Modify value	Redundancy check CRC16-2
80	06	9C 7E	00 85	LSB:18 MSB:30

The modification is invalid if the modified address is out of range.Return error instruction:

Slave address	Function code	Error code	Redundancy check CRC16-2
80	06	02	LSB MSB

The address modification instruction is used to modify any current address value to the required value when the address originally set by the sensor is known.Modify any current address value to the required value through. Address modification range:0x80~0xF4.The effective range of the address setting is 0x80 ~ 0xF4, and the modification of address takes effect after the power is turned on again.

For example:The address originally set by the sensor is known,and you want to set the address to 0x81
Then send instructions via RS485 bus:80 06 9C 7E 00 81 19 F3
The address originally set by the sensor is known,and you want to set the address to 0x82
Then send instructions via RS 485 bus:81 06 9C 7E 00 82 58 23

Return:If the setting is successful,the original instruction will be returned;If it fails,an error instruction will be returned.

4.Master station request message format(Modify the baud rate):

Slave address	Function code	Address where data is stored	Modify value	Redundancy check CRC16-2
80	06	9C 7F	MSB:00 LSB:02	LSB:09 MSB:92

MSB defaults to 00;The LSB bit of the modified value:Baud rate setting,as follows:

1,200	57600	38400	19200	9600
01	02	03	04	05

After setting successfully,slave station response message format:

Slave address	Function code	Address where data is stored	Modify value	Redundancy check CRC16-2
80	06	9C 7F	MSB LSB	LSB MSB

If it is not within this range,this operation is invalid.The return operation error command:

Slave address	Function code	Error code	Redundancy check CRC16-2
80	86	02	LSB MSB

The baud rate modification command is used when the baud rate originally set by the sensor is known. Modify any current baud rate value to the required value through the baud rate modification instruction. Address modification range:115200, 57600, 38400, 19200, 9600(Level 5). The default baud rate of the slave is 0x01(115200).The effective range of the baud rate setting is 0x01~0x05

For example:The baud rate originally set by the sensor is known to be 115200,at this time,you want to set the baud rate to 57600.
Then send instructions via RS485 bus:80 06 9C 7F 00 02 09 92
The baud rate originally set by the sensor is known to be 115200,at this time,you want to set the baud rate to 9600
Then send instructions via RS485 bus:80 06 9C 7F 00 05 48 50

Return:If the setting is successful,the original instruction will be returned;If it fails,an error instruction will be returned.

5.Master station request message format(Switching logic setting):

Slave address	Function code	Address where data is stored	Modify value	Redundancy check CRC16-2
80	06	9C 74	MSB:00 LSB:00	LSB:F9 MSB:91

After setting successfully,slave station response message format:

Slave address	Function code	Address where data is stored	Modify value	Redundancy check CRC16-2
80	06	9C 74	MSB:00 LSB:00	LSB:F9 MSB:91

The switch logic setting instruction is used to modify any current output logic to the required logic value. Modification range: NPN,PNP,PUP(three kinds).

For example:The sensor now wants to set the switching value to NPN
Then send commands via RS485 bus:80 06 9C 74 00 00 F9 91
The sensor now wants to set the switching value to PNP
Then send commands via RS485 bus:80 06 9C 74 00 01 38 51
The sensor now wants to set the switching value to PUP
Then send commands via RS485 bus:80 06 9C 74 00 02 78 50

Return:If the setting is successful,the original instruction will be returned;If it fails,an error instruction will be returned.

6.Master station request message format(Switch state setting):

Slave address	Function code	Address where data is stored	Modify value	Redundancy check CRC16-2
80	06	9C 73	MSB:00 LSB:00	LSB:48 MSB:50

After setting successfully,slave station response message format:

Slave address	Function code	Address where data is stored	Modify value	Redundancy check CRC16-2
80	06	9C 73	MSB:00 LSB:00	LSB:48 MSB:50

The switch status setting instruction is used to modify any current output status to the required logic value. Modification range: NO, NC(Two kinds)

For example:The sensor now wants to set the switching value to NPN
Then send commands via RS485 bus:80 06 9C 73 00 00 48 50
The sensor now wants to set the switching value to PNP
Then send commands via RS485 bus:80 06 9C 73 00 01 89 90

Return:If the setting is successful,the original instruction will be returned;If it fails,an error instruction will be returned.

7.Master station request message format(Filter times setting):

Slave address	Function code	Address where data is stored	Modify value	Redundancy check CRC16-2
80	06	9C 77	MSB:00 LSB:00	LSB:09 MSB:91

After setting successfully,Slave station response message format:

Slave address	Function code	Address where data is stored	Modify value	Redundancy check CRC16-2
80	06	9C 77	MSB:00 LSB:00	LSB:09 MSB:91

The order of filter times is used to set any current filter times as the required filter value. Modification range:Fast, Medium, Slow(three kinds).

For example:He sensor wants to set the number of filtering times to fast(1st Filtering)
Then send instructions via RS485 bus:80 06 9C 77 00 00 09 91
He sensor wants to set the number of filtering times to medium(8st Filtering)
Then send instructions via RS485 bus:80 06 9C 77 00 01 C8 51
He sensor wants to set the number of filtering times to slow(20st Filtering)
Then send instructions via RS485 bus:80 06 9C 77 00 02 88 50

Return:If the setting is successful,the original instruction will be returned;If it fails,an error If it fails,an error instruction will be returned.

8.Master station request message format(Reset):

Slave address	Function code	Address where data is stored	Modify value	Redundancy check CRC16-2
80	06	9C 87	MSB:00 LSB:01	LSB:C8 MSB:62

After setting successfully,Slave station response message format:

Slave address	Function code	Address where data is stored	Modify value	Redundancy check CRC16-2
80	06	9C 87	MSB:00 LSB:01	LSB:C8 MSB:62

The reset Settings command is used to restore factory Settings.

Send instructions:80 06 9C 87 00 01 C8 62
Return:If the setting is successful,the original instruction will be returned;If it fails,an error If it fails,an error instruction will be returned.

9.Error feedback:

Address and CRC check errors will not receive the slave data feedback, other errors will be returned to the host error code.The second (function code) of the data frame plus 0X80 indicates an error in the request(illegal function code,illegal data value).If the second part of the data frame (function code) plus 0X80 is greater than 0XFF, the second part returns 0XFF.

(1).The following error instruction is returned(illegal function code):

Slave address	Function code	Error code	Redundancy check CRC16-2
80	91	01	LSB MSB

If the function code is not 0X03 or 0X06, the function code is invalid.

For example:Send instructions:80 11 9C 74 00 00 8D 92 Return:80 91 01 DC 78
Send instructions:80 88 9C 74 00 00 91 8E Return:80 FF 01 F0 18

(2).he following error instruction is returned(illegal Register address):

Slave address	Function code	Error code	Redundancy check CRC16-2
80	86	02	LSB MSB

When the register address is wrong, it is considered an illegal function code. For example:Send instructions:80 06 9C 00 00 00 B9 8B Return:80 86 02 93 89

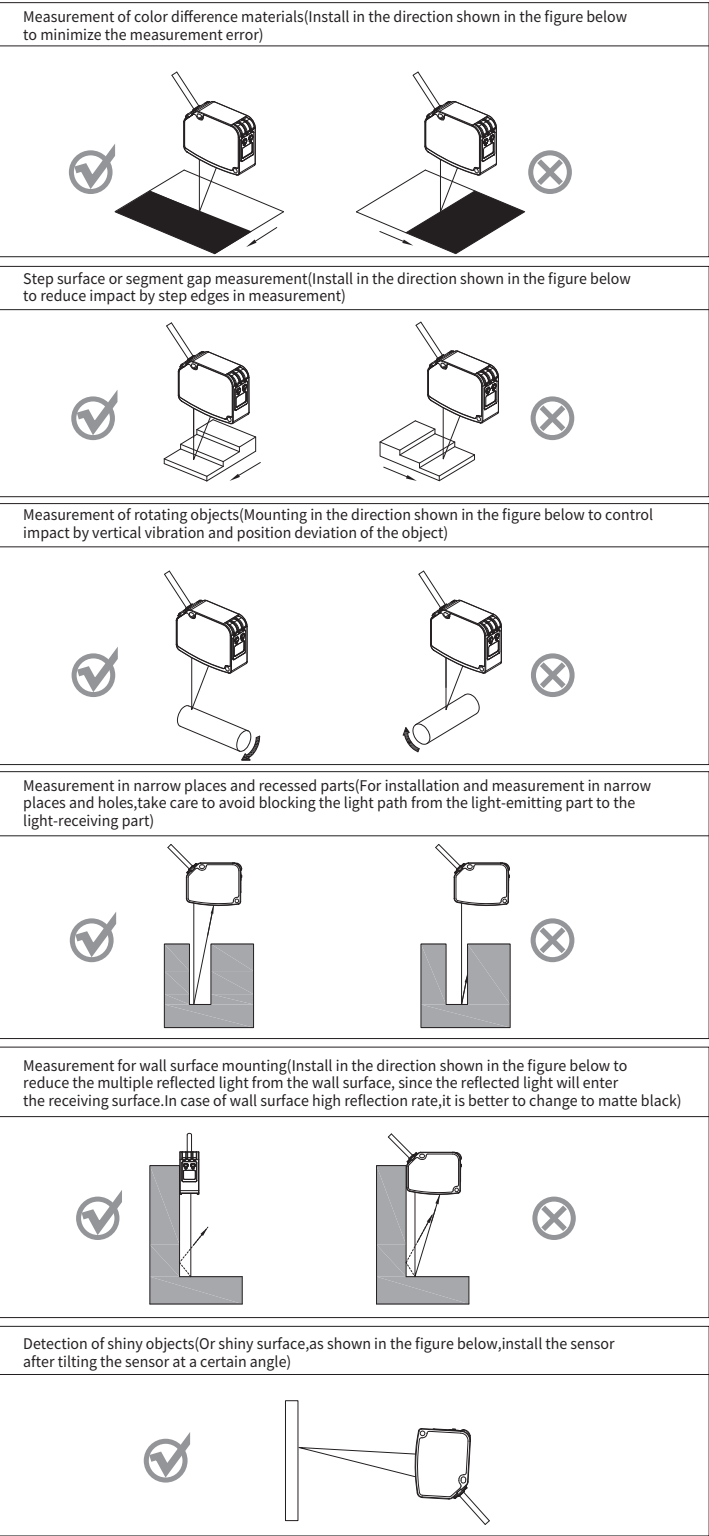
(3).he following error instruction is returned(illegal data value):

Slave address	Function code	Error code	Redundancy check CRC16-2
80	86	03	LSB MSB

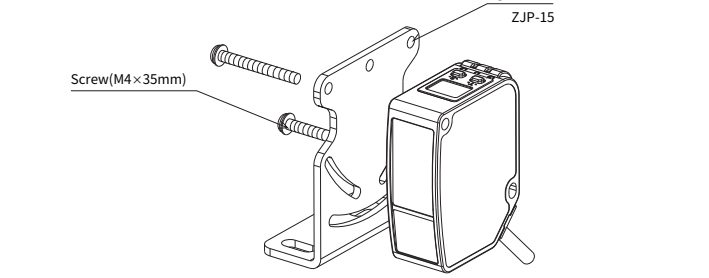
When the register address is wrong, it is considered an illegal Data value.

For example:Send instructions:80 06 9C 74 00 06 79 93 Return:80 86 03 52 49

■ Installation precautions



■ Installation



*For mounting, please keep tightening torque < 0.5N·m

PS-PDB-2023LB V3
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